Lexium integrated drives
ILS1 with I/O interface for motion sequence
ILS1 with 3-phase stepper motor

References												
Example:	**I**	**L**	**S**	**1**	**M**	**5**	**7**	**1**	**P**	**B**	**1**	**A**
Motor type **S** = 3-phase stepper motor	I	L	**S**	1	M	5	7	1	P	B	1	A
Supply voltage **1** = 24 ... 36 V	I	L	S	**1**	M	5	7	1	P	B	1	A
Communication interface **M** = I/O interface for motion sequence	I	L	S	1	**M**	5	7	1	P	B	1	A
Flange size **57** = 57 mm **85** = 85 mm	I	L	S	1	M	**5**	**7**	1	P	B	1	A
Motor length ("L") *(1)* **1** = motor length "L" **2** = motor length "L" **3** = motor length "L"	I	L	S	1	M	5	7	**1**	P	B	1	A
Winding type **P** = medium speed of rotation, medium torque **T** = high speed of rotation, medium torque *(2)*	I	L	S	1	M	5	7	1	**P**	B	1	A
Connection technology **B** = printed circuit board connector **C** = industrial connector	I	L	S	1	M	5	7	1	P	**B**	1	A
Measurement system **1** = index pulse	I	L	S	1	M	5	7	1	P	B	**1**	A
Holding brake **A** = no holding brake **F** = with holding brake *(3)*	I	L	S	1	M	5	7	1	P	B	1	**A**

(1) The motor length "L" depends on the mechanical characteristics, see pages 4/82, 4/85 and 4/87.
(2) Winding type T only with ILS1M853.
(3) Holding brake only with ILS1M85.

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